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# Ship-based Oceanwide Observation of Sea Surface Heights in Consideration of Hydrodynamic Corrections

Jörg Reinking, Alexander Härting

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## MOTIVATION

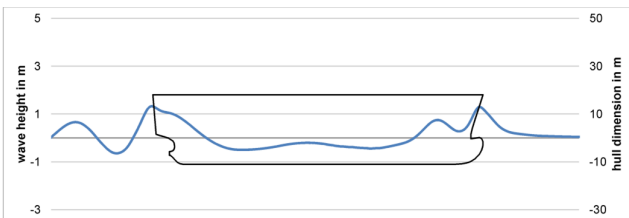
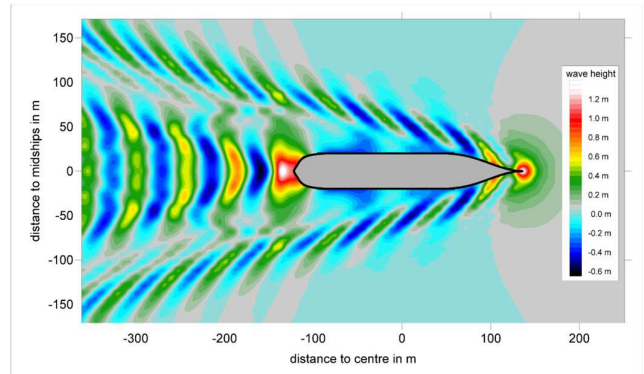


- Sea Surface Heights (SSH) observed
  - locally: tide gauge
    - only at coasts
    - data valid only at observation site
    - spatial interpolation: hypothetical behaviour must be assumed
  - globally: satellite altimetry
    - many systematic effects, calibration required
    - still problematic close to coast
    - spatial and temporal resolution restricted
  - GNSS aboard ships?

- Ship-based SSH observation using GNSS

- seems to be easy: applied by many groups for different purposes
- BUT: hydrodynamic behaviour
  - completely neglected
  - not considered
  - wrongly considered
  - considered approximately

**wave system of a moving ship extends over a large area**

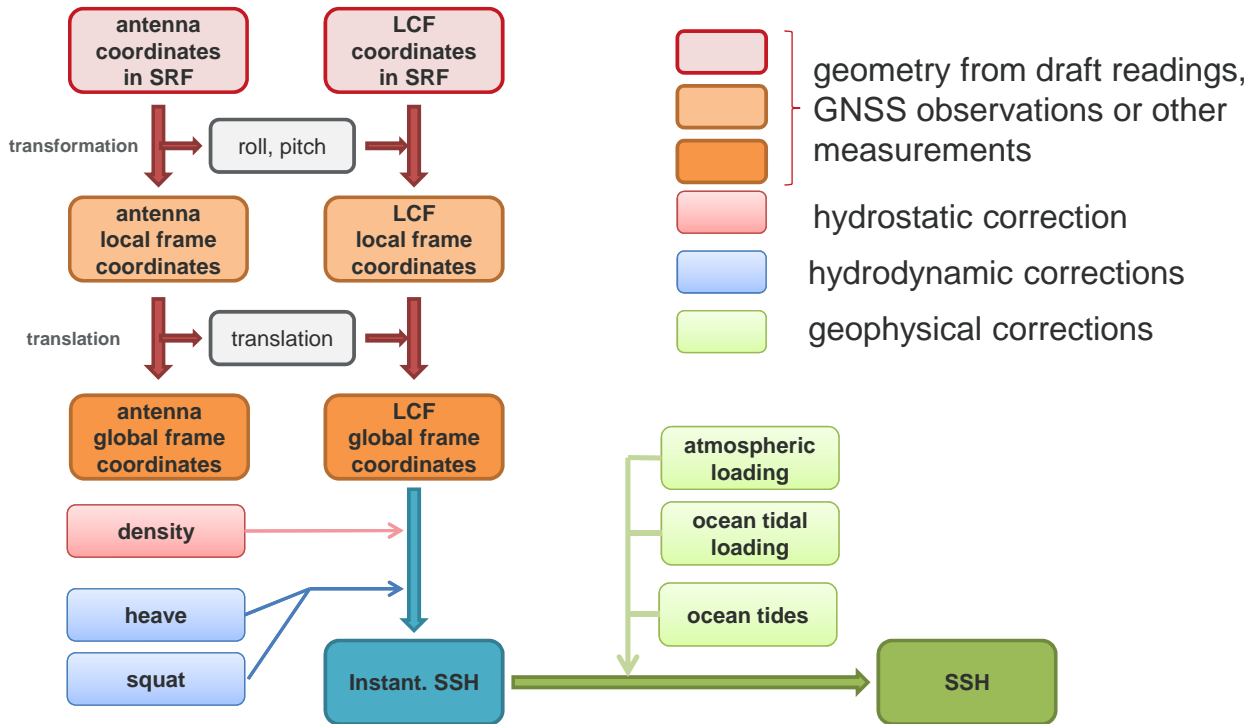


**ship squat:  
a moving ship will experience  
a change of sinkage and trim**

- SSH from observed GNSS antenna heights at ships

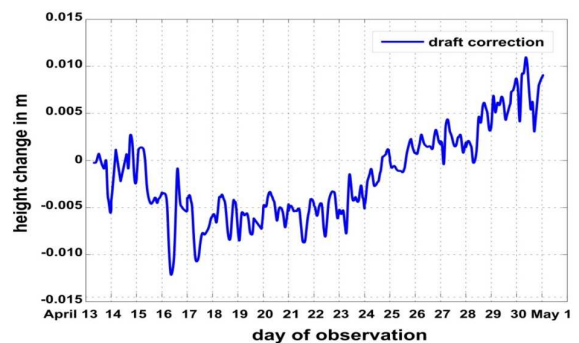
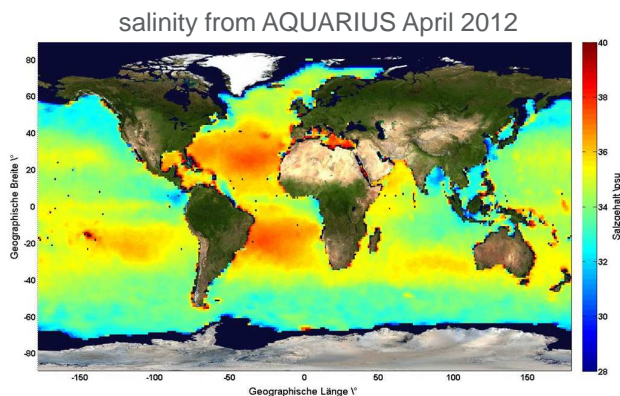
- Assumptions

- three GNSS receivers aboard the ship
- coordinates in a global reference frame from PPP or differential solution for at least one GNSS receiver available
- 3D coordinate differences between antennas from a “moving baseline” differential solution in a local frame
- precise position changes in time from epoch-to-epoch double difference GNSS solution for every single antenna
- antenna coordinates in ship reference frame (SRF) known from static measurements
- Longitudinal Centre of Floatation (LCF) as height reference point, SRF coordinates from e.g. ship’s loading computer

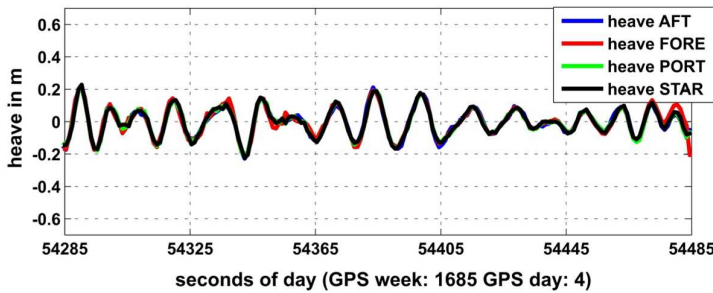


## ● density:

- draft computed with assumed salinity and temperature
- differs from actual salinity (e.g. from AQUARIUS satellite)
- draft correction from ship's particulars or volume of hull model

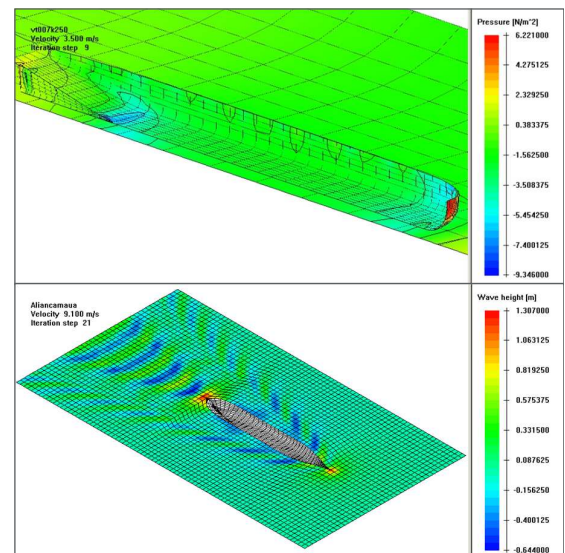
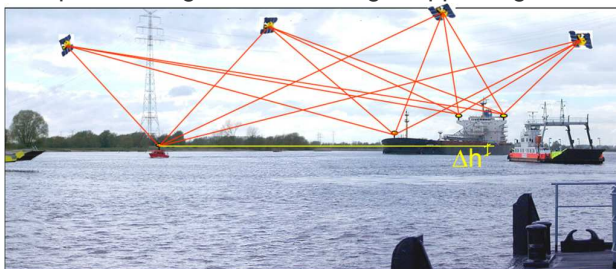


- density:
  - draft computed with estimated salinity and temperature
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- heave:
  - epoch-to-epoch double difference GNSS solutions
  - corrected for roll and pitch changes
  - accumulated and high-pass filtered

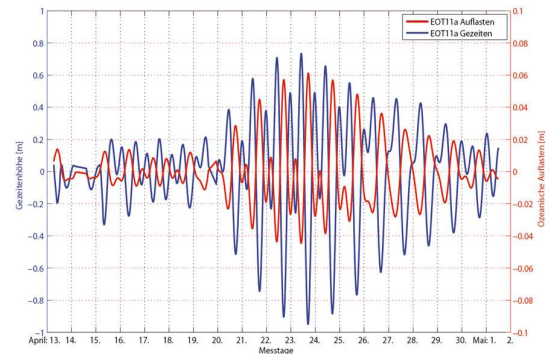


heave at LCF: mean of heave at GNSS antennas

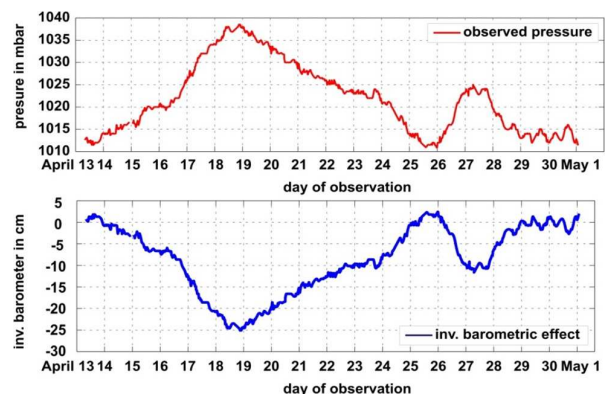
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- squat:
  - Computational Fluid Dynamics (CFD) simulations
  - full scale calibration experiment
  - speed through water from e.g. Doppler log



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- **ocean tide / ocean tidal loading:**
  - tidal models FES2004, DTU10, EOT11a etc.
  - SPOTL software (Agnew)

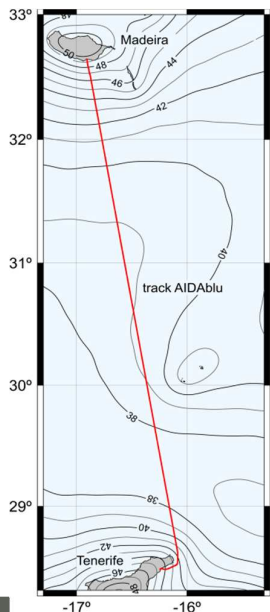


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- ocean tide / ocean tidal loading:
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  - SPOTL software (Agnew)
- **atmospheric loading:**
  - atmospheric pressure from ship's barometer
  - calculation of Inverse Barometer IB



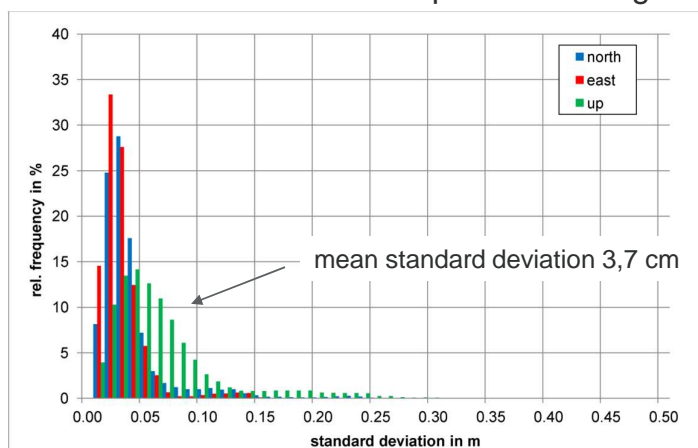


- cruise vessel *AIDAblu* between Tenerife and Madeira, March 2011
- escort craft for calibration experiment: *Oceanodromo*
- main purposes:
  - test of SHIPS calibration method in open ocean
  - quality estimation of resulting instantaneous SSH using PPP



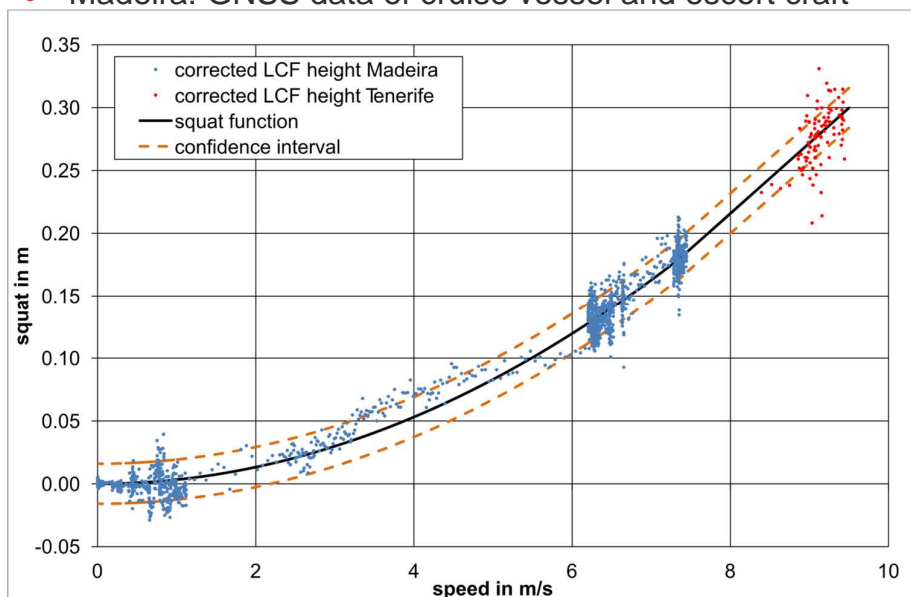
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- GNSS processing
  - comparison of coordinate differences between antennas
    - from “moving baseline” solution (own software)
    - from PPP solution (Bernese 5.0)
  - detect and eliminate gross errors
    - eliminate epochs showing larger discrepancies

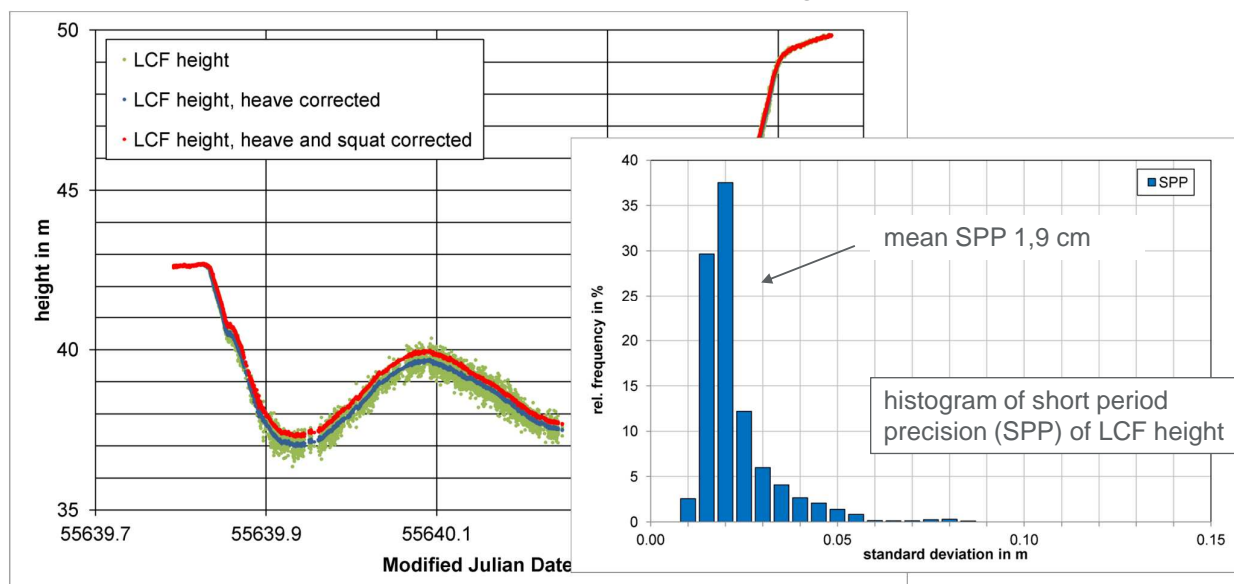


histogram of standard deviation from translational transformation of “moving baseline” solution to PPP solution

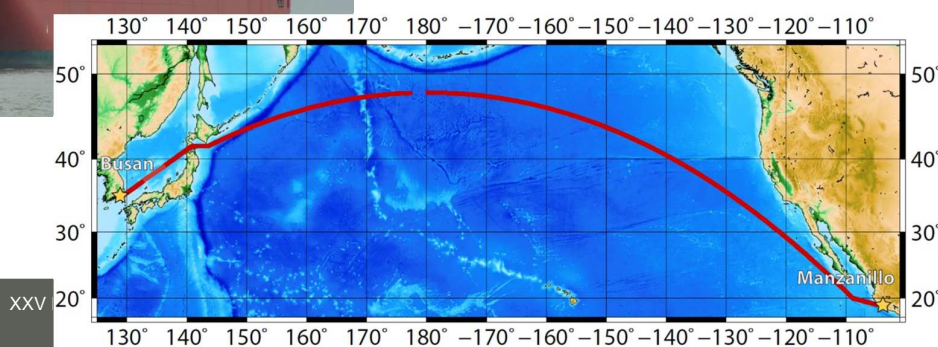
- squat correction
  - Tenerife: GNSS and tide gauge data
  - Madeira: GNSS data of cruise vessel and escort craft



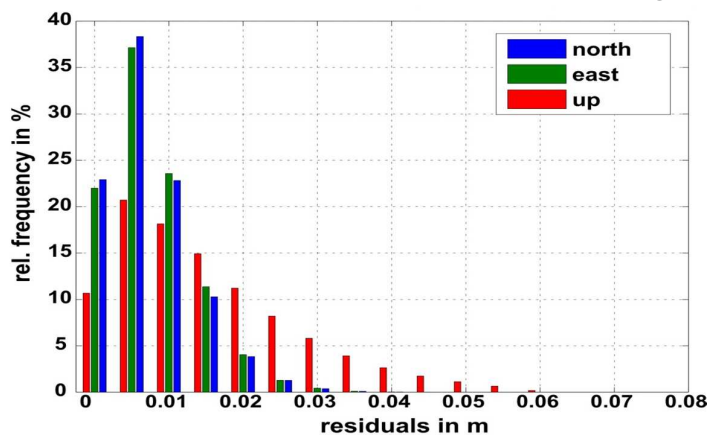
- instantaneous SSH
  - short period precision (SPP): standard deviation of the mean value of the derived SSH over an interval with a length of 500 m



- container vessel *Monte Verde* between Korea and Mexico, April/May 2012
- main purposes:
  - test over large distance, long period under practical and routine conditions
  - comparison to altimeter data



- GNSS processing
  - comparison of coordinate differences between the two dual-freq.-antennas
    - from “moving baseline” solution (own software)
    - from PPP solution (NRCan online service)
  - detect and eliminate gross errors
    - eliminate epochs showing larger discrepancies

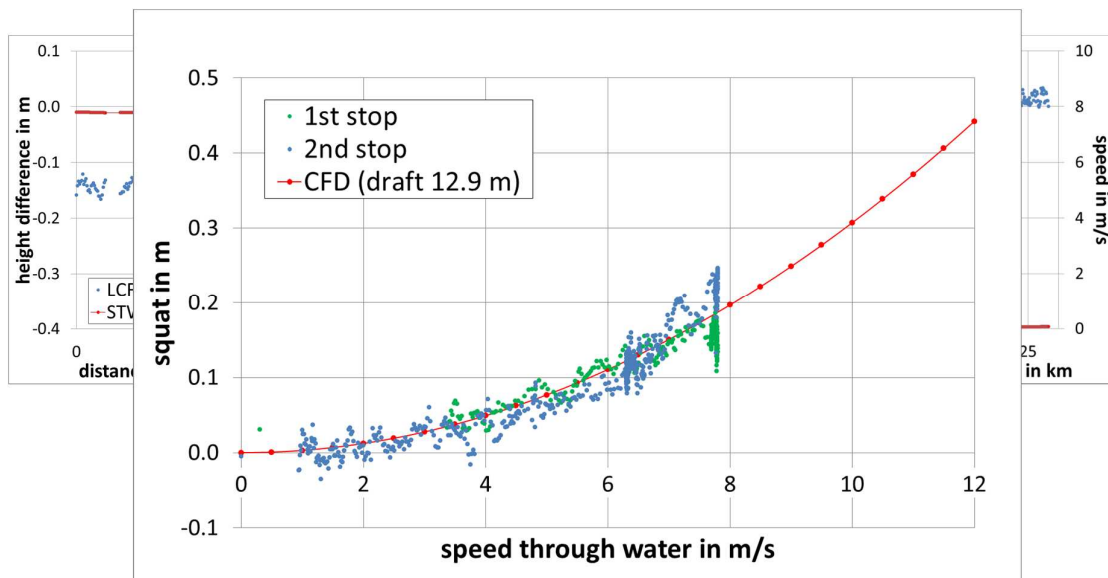


mean standard deviation 1,7 cm

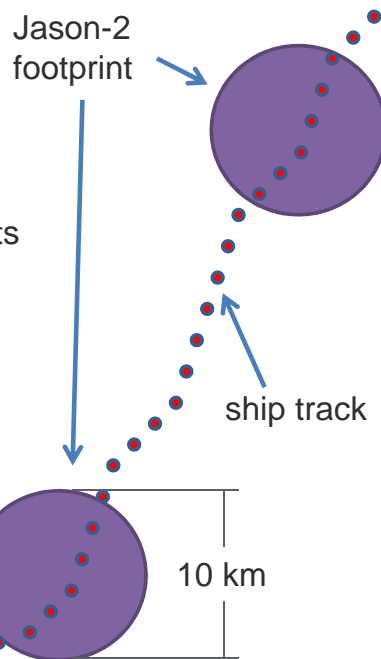
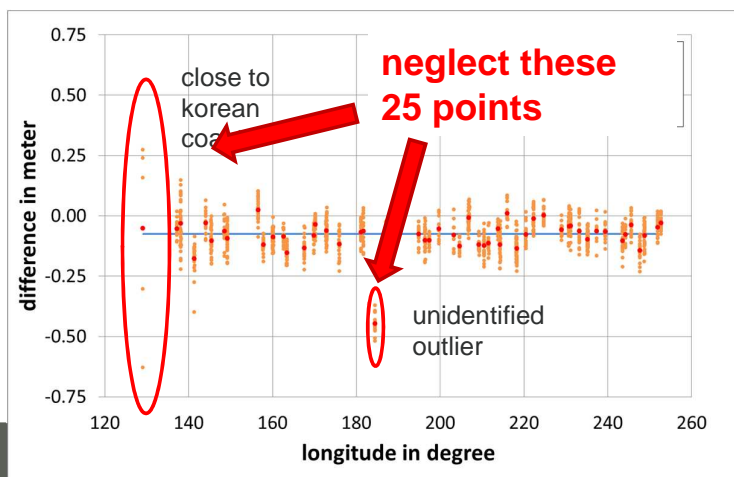
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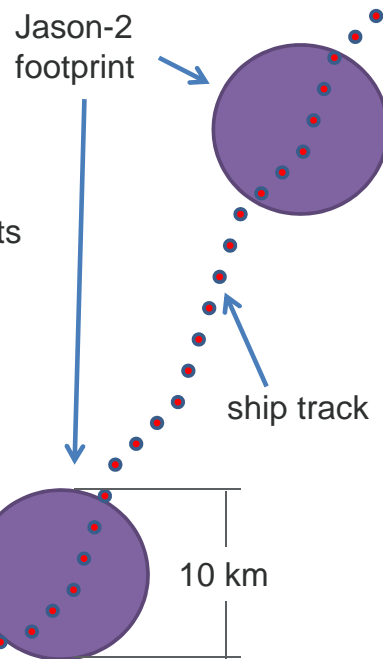
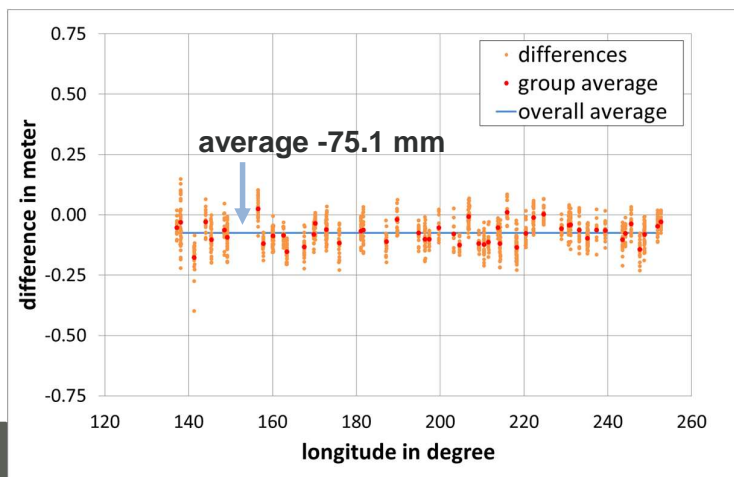
- squat correction
  - hull model available: CFD simulation for unrestricted water
  - two stop maneuvers for engine maintenance



- comparison with SSH from altimetry (Jason-2)
  - cross-over points: all footprints within a distance of less than 5 km from ship's position
  - in total 1342 cross-over points
  - regular pattern of Jason-2 tracks: cross-over points form groups at almost the same longitudes



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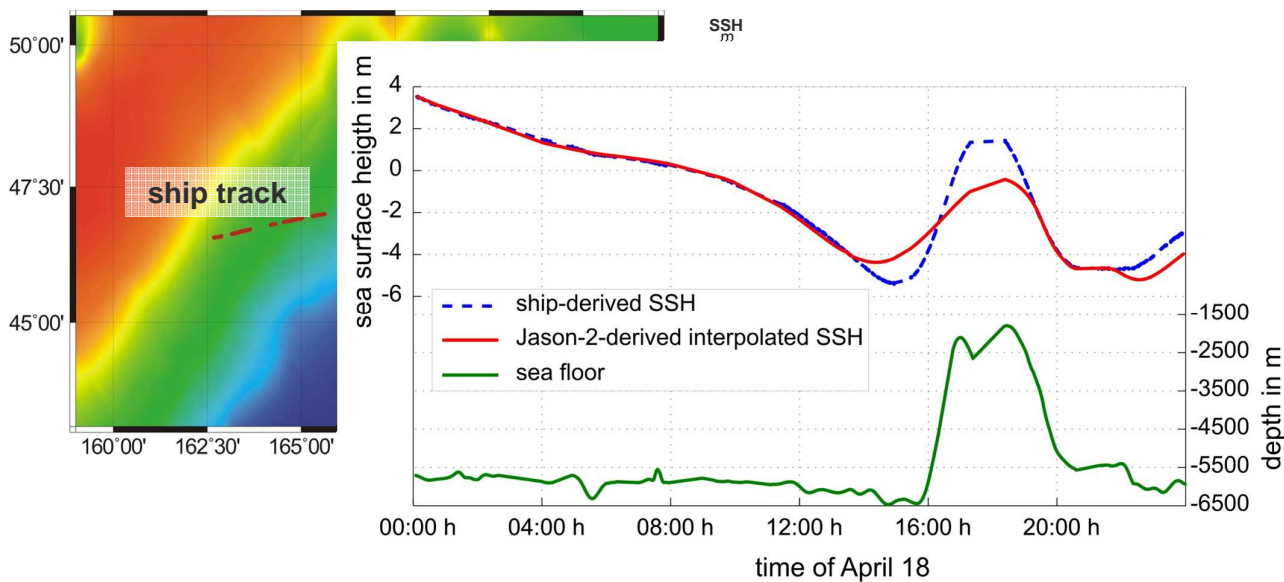
## CONCLUSION

- measurements can be done on almost any kind of ship
- use of merchant vessels would open up a new, continuous data source
- determination of antenna heights from GNSS limits the precision
- ship-based SSH determination is consistent with satellite altimetry results
- allows cross-wise validation over large areas
- ship-based observations could be a significant complement to remote sensing methods

Thank you for your attention

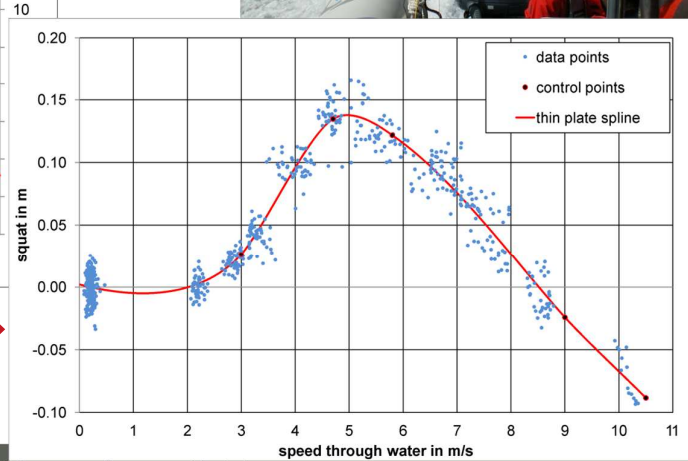
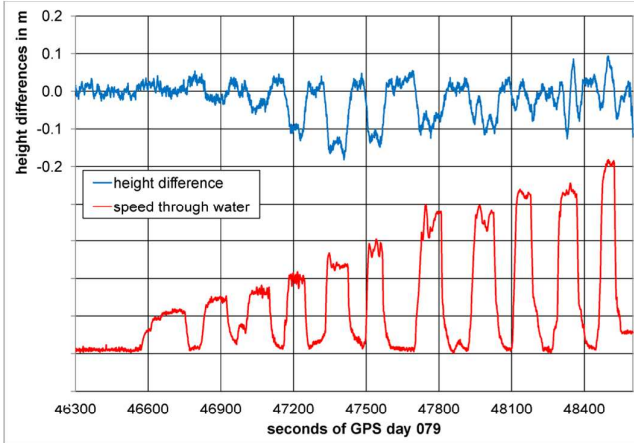
EXPERIMENT: PACIFIC OCEAN

- comparison with SSH from altimetry (Jason-2)
  - spatial resolution: interpolated SSH from Jason-2 at the Hawaii-Emperor seamount chain



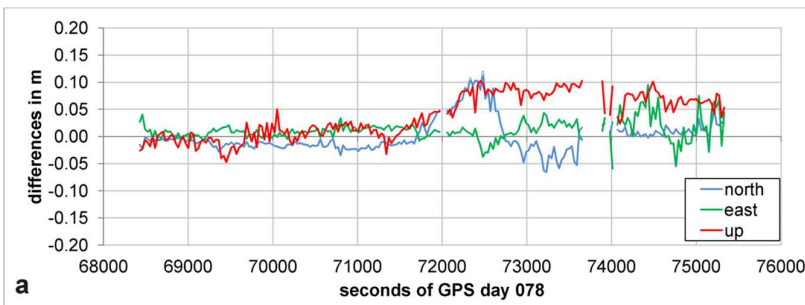
# CALIBRATION ESCORT CRAFT

- inverted SHIPS method at the berth:
  - LCF as height reference
  - escort craft operated at various speeds



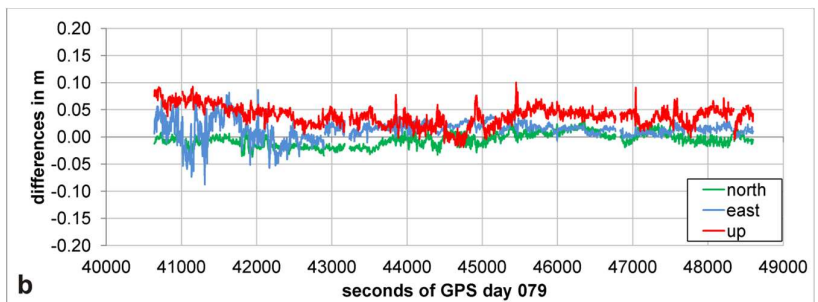
# COMPARISON PPP

- PPP solution and differential kinematic solution, reference stations in Tenerife and Madeira



departure Tenerife

arrival Madeira



- GNSS measurements at berth
- additionally: tide gauge readings, draft readings, LCF position in SRF

